## **Institute of FIeld roBOtics (FIBO)**

A Cradle of Future Leaders in Robotics

То

present very expensive.

## **Portable Balancing Machine**

vibrational parts, we need to know the

magnitude and phase difference of vibrating

signals, representing unbalancing situation.

This signals will be measured by tracking filter

circuits, either analog or digital systems.

Unfortunately, this Tracking filter circuit is at

building inexpensive balancing machines which

are easy to operate by just using offline

programming. This program employs function

to determine the linear independent function

fitting and unbalancing signals, leading to

function fitting. During this signal process, data

are completely recorded in one rotating period.

research either sine or square depends on speed

and precision of a processor unit. Therefore,

this research inevitably introduces a Fast Fitting

Algorithm that can be used in either low speed

observed by sampling rate, quantization or bit

interface by proposing both sequence and

depend on user experience and expert systems which are used to help a decision making

processor or microprocessor.

length and signal to noise ratio.

random access for the users.

process.

fitting that allows us to use lower cost circuits.

This research aims at designing and

The fundamental idea of this research is

A mathematical function used in this

The precision of equipment can be

We develop a user-friendly graphic

The success in balancing occasionally

balance heavy machines with

Our expert system is a crucially importance that helps us to distinguish the difference between misalignment and beating. Additionally, ill conditions in finding the influence coefficient matrix in two plane is the fundamental results of trial and error in balancing machines.

The general specification of our portable balancing machine are: -instant correcting mass calculation -one run balancing -100 machine status recording -sequence and random operation -n<sup>th</sup> harmonics detecting -number of averaging setting -simple vibration inspection:  $\Phi$  & Amp -more than 10 cm distance  $\Phi$  detecting -infrared phase detecting -adjustable signal amplifier gain -dark or light  $\Phi$  detection -AI machine condition diagnostic (under



development)



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